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FTP-642MCL301/302 PRODUCT SPECIFICATIONS

DATE DOCUMENT CONTROL SECTION



				TITLE FTP-642MCL301/302 PRODUCT SPECIFICATIONS	
				DRAW No. A1NA02243-0301/6	
				FUJITSU TAKAMISAWA COMPONENT LIMITED	
EDIT	DATE	DESIGN	CHECK	DESCRIPTION	SCALE
DESIGN	01.03.17	Y.Yada	CHECK	APPLY K.Maeda	1/1

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1. Guideline for product recycling

- Fujitsu Takamizawa Component Co., Ltd. is making an effort to promote the environmental management per ISO 14001 with a policy "Better corporate activities while valuing the environment"
- The below lists the components and their materials used in this printer. Refer this list when the printer is to be recycled.

FTP-642MCL301/302 List of materials

No.	Name of components	Material
1	Printer frame	PPO resin (with GF)
2	Gear cover	POM resin
3	Rubber roller	Silicone rubber + SUS
4	Platen gear, middle gears 1, 2	POM resin
5	Pulse motor	SPCC + iron + copper wire
6	Motor FG plate	SUS
7	Sensor fixture	ABS resin
8	Knob	ABS resin
9	FG plate	SUS
10	Head-up arm	Zinc alloy
11	Head-up lever	POM resin
12	Thermal head	Aluminum + ceramic substrate
13	Head pressurizing shaft	SUS
14	Head support board	SPCC
15	Head pressurizing spring	SUS
16	Arm spring	SUS
17	Spring (Only MCL301)	SUS
18	Pinch roller (Only MCL301)	POM resin
19	Bearing	Sintered alloy
20	FG coil spring	SUS
21	Guide film (Only MCL301)	PET resin
22	Auto cutter	*1)

Please refer to specifications of FTP-642CT001

"Abbreviations for the materials used"

- SUS: Stainless steel
- POM: Polyacetal resin
- PET: Poly(ethylene terephthalate)
- PPO: Poly (phenylene oxid) resin
- SPCC: Rolled steel plate
- PI: Polyimide
- GF: Fiberglass resin

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2. Scope

This specification applies to FTP-642MCL301/302.

The following standard interface board or drive LSI and reference circuits satisfy the specifications in this manual:

So details of cutter, please refer "FTP-642CT001 PRODUCT SPECIFICATIONS".

- (1) Standard interface board: FTP-622DCL001
- (2) Drive LSI: FTP-622CU101

3. Description

This printer is a compact and light high-speed printer equipped with a line dot thermal head with 8-dot/mm resolution.

4. Configuration

This printer is composedated 3 blocks-printer mechanism, cutter and attachment.

Printer mechanism : FTP-642MCL001 (for FTP-642MCL301)
 :FTP-642MCL002 (for FTP-642MCL302)

Cutter :FTP-642CT001

The configuration of this printer (mechanical unit) is shown below.

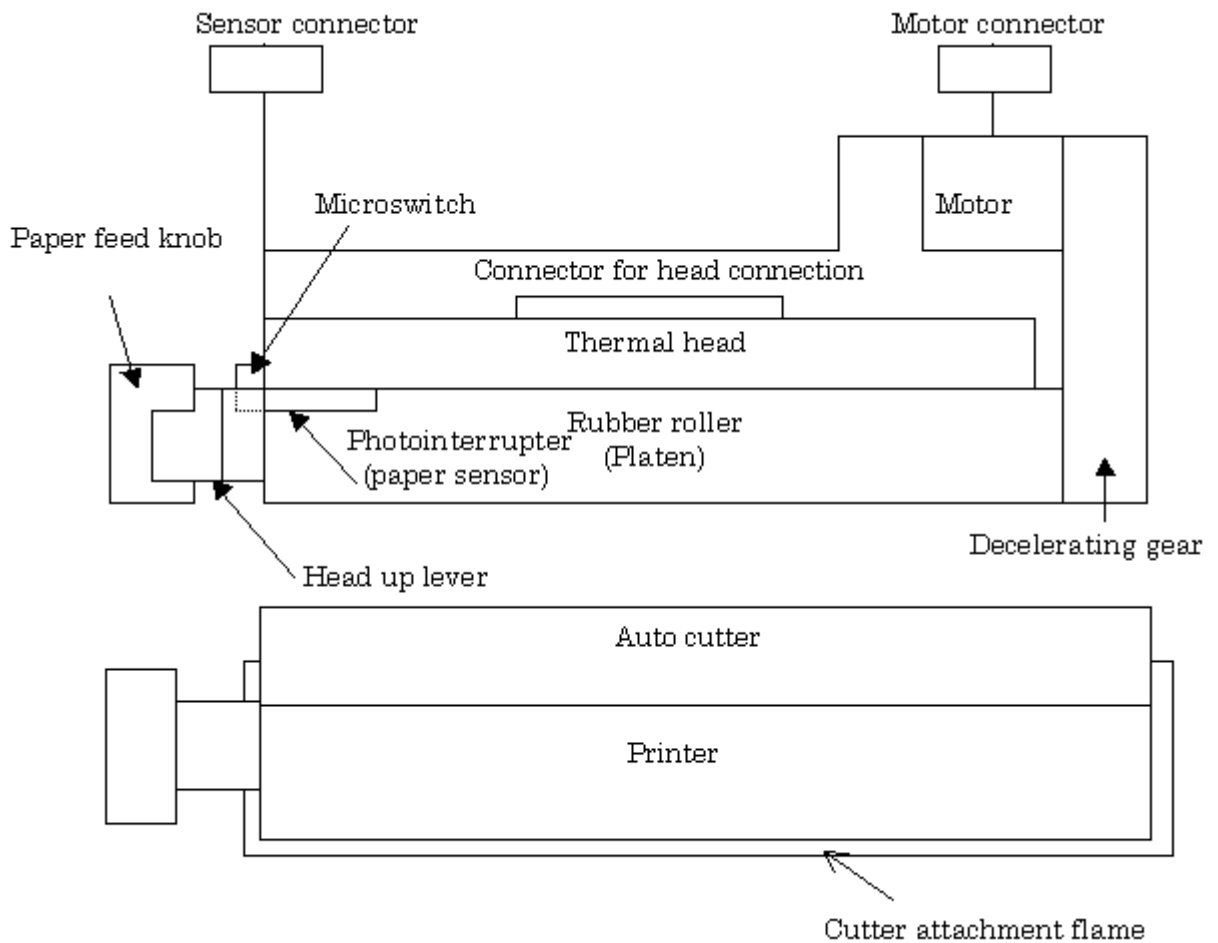


Figure 1 Printer configuration

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5. General Specifications

ITEM		SPESIFICATION
Printing specifications	Printing method	Thermal sensitive line dot method
	Effective printing width	104mm
	Head configuration	832 dots / line
	Dot pitch	0.125(vertical direction) x 0.125(horizontal direction)
	Print density	OD 0.8 or higher at the F&T standard printing condition when the specified paper is used. *Measuring instrument : SAKURA densitometer PDA-65 from Konica Co.,Ltd.
	Printing speed	At 24V drive Maximum 80mm / second (640 dot lines / second) At standard paper and F&T high-speed printing mode.
Specified paper(*1)	High-sensitivity paper	TF50KS-E4 NIPPON PAPER
		TF50KS-E NIPPON PAPER
	Standard paper	PD150R OJI PAPER
		TF60KS-F1 NIPPON PAPER
		P220VBB-1 MITSUBISHI PAPER
	Medium-term preservable paper	PD170R OJI PAPER
		TP50KJ-R NIPPON PAPER
		AFP-235 MITSUBISHI PAPER
Long-term preservable paper	PD160R OJI PAPER	
Paper width		MCL301 : 112 ^{+0.1} mm (front insertion) MCL302 : 114 ^{+0.1} mm (rear insertion)
Paper feed method		Friction feed (1 dot line / 4 pulse, bipolar 1-2 phase excitation)
Paper feed accuracy		±5% at fixed-speed feed with the back tension of approx.100g(0.98N) (±2% at 25°C and 60%RH)
Line gap in one print line by enable drive		Gap between right and left print line in the same line dot line : 0.125mm
Detection function	Head temperature detection	Thermistor
	Paper detection	Photointerrupter
	Mark detection	
	Head up detection	Microswitch
	Home-position detection	Microswitch
External dimensions(W x D x H)		149mm x 68mm x 39mm (excluding the lever and knob)
Mass		Approx. 500g

*1 For using unspecified paper, both sides shall consult and evaluate and check it to determine whether to use it.

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ITEM			SPESIFICATION
Operating power	Head	For printing	Voltage : 24 VDC ±5% Current : peak current of approx.4.1A (2-part divided drive, Printing rate : 50% printing speed : 80mm/sec, head resistance value : 1275 Ω)
		For logic	Voltage : 5 VDC ±5% Current : Maximum 0.3A
	Motor drive		Voltage : 24 VDC ±5% Current : Maximum 1.0A (by the F&T standard constant-current drive circuit)
Environmental characteristics	Operating temperature and humidity(*2)		5°C to 40°C, 20 to 85%RH No condensation
	Storage temperature and humidity		-20°C to 60°C, 5 to 95%RH No condensation paper is excluded
	Noise		60 dB or less at 1m from the surface of the printing mechanism
Reliability (*3)	Vibration (non-operation)		10 to 55 to 10 Hz, one-side amplitude 0.15mm,1 octave/minute, maximum 1G 20 cycles for each of X, Y, and Z directions
	Impact (non-operation)		50G, 11ms, half-sine wave, 5 times for each of the X, Y, and Z directions
	Pack drop		75cm drop for 6 surface, corner and ridges in pack
	Temperature and humidity cycle (non-operation)		Two successive cycles of -25°C (2 hours) to room temperature (2 hours) to 65°C and 85% RH (2hours) to room temperature (2hours)
Life	Electrical life		1 hundred million pulses (at the F&T standard printing condition)
	Mechanical life		Paper length : 50 km (printing rate : 25% or less)
	Life of the head up lever		5000 or more times when one up and down are counted as one time
	Photointerrupter life		1.2 x 10 ⁴ hours (time while the current is conducted) with the specified circuit
	Cutting life		300 thousand times or more(cutting cycle is 2 s or longer)
Printing start position at the left end			MCL301 : 4±1 mm , MCL302 : 5±1 mm from the paper edge to the print start position. This value is : 1. When the paper of 112mm (MCL301) and 114mm (MCL302) width is used 2. When 1-ply long-term perceivable paper is used 3. When no paper jam or collapse occurs
Paper positioning by mark detection			Approx. 7.5mm (MCL301) and 10.2mm (MCL302) from the mark end position to heating element. This value is when paper is inserted from front, fixed-speed feed is used, and paper feeding by marking detection is the default (2mm).

*2 The print density is guaranteed in this range. The printer can operate from 0°C to 50°C.
*3 After the test, the printing specifications shall be satisfied.

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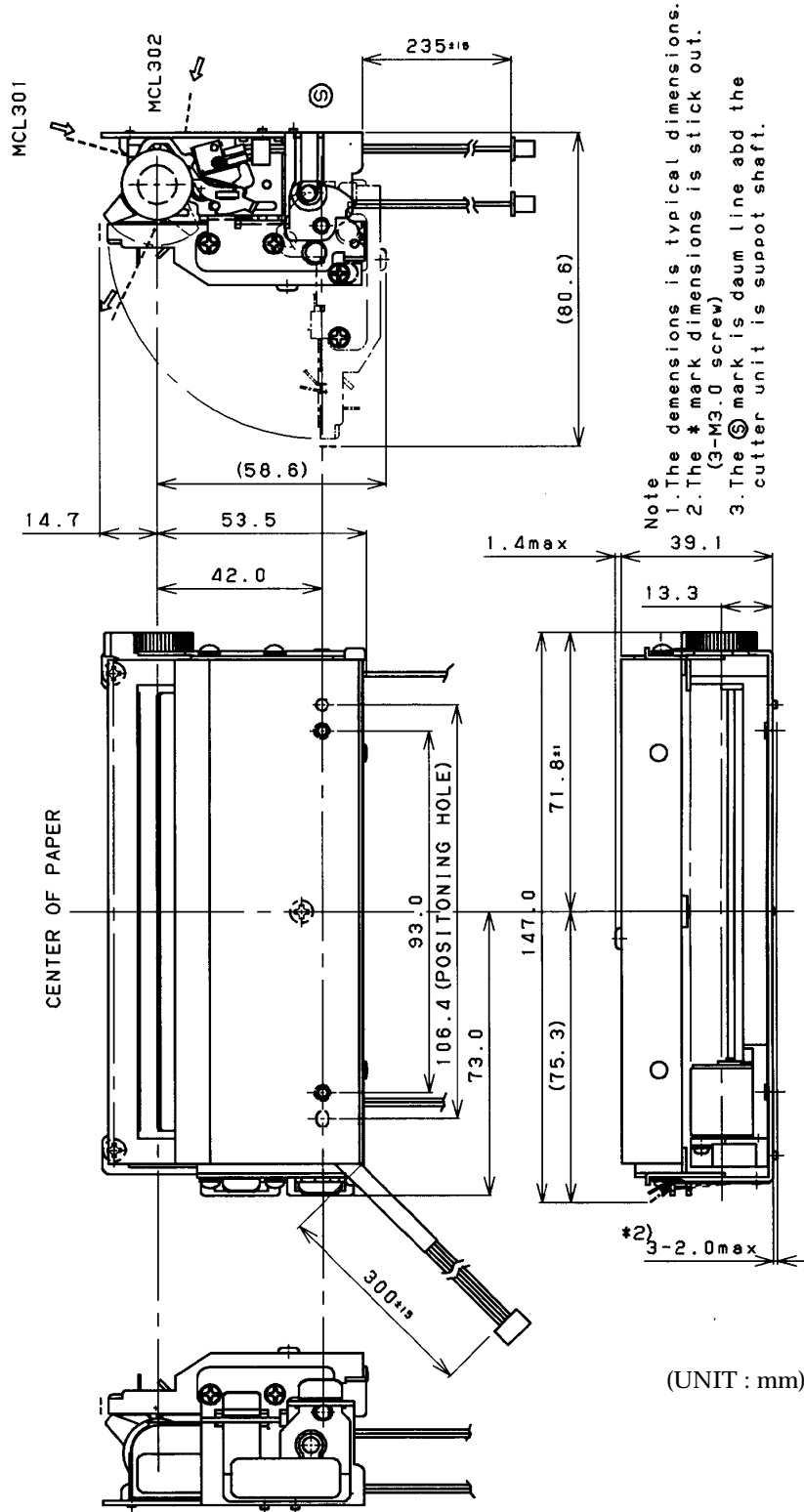
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6. External Dimensions and Mounting Positions

(1) External dimensions

Figure 2 shows the external dimensions.

Figure 2 FTP-642MCL301/302 outview dimensions



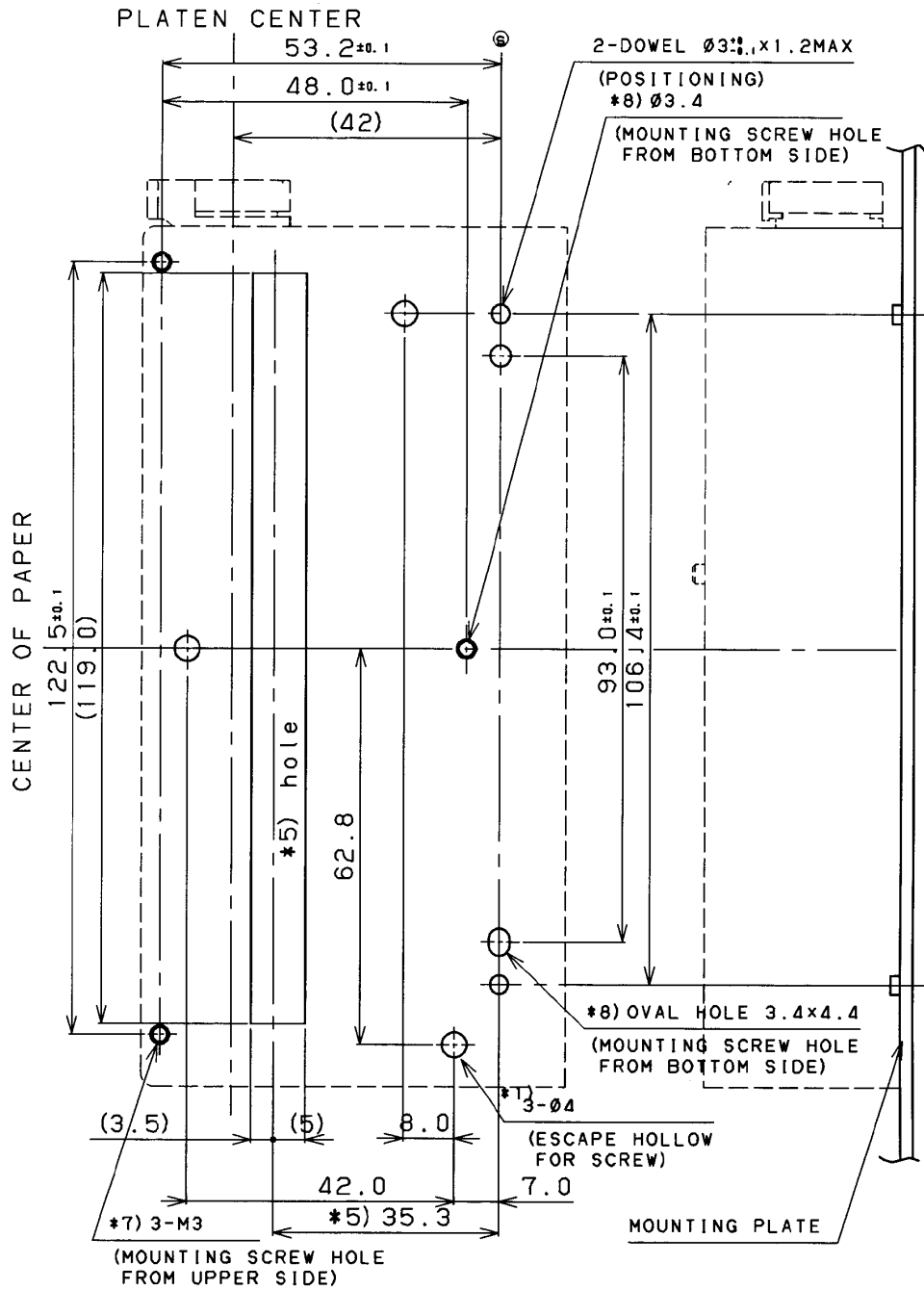
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(2) Mounting positions

Figure 3 shows the mounting dimensions of this printer.



(UNIT: mm)

NOTES)

1. Please make hollow of $\varnothing 4 \times 2$ mm in order to escape screw projection in three positions.
2. The dimension tolerance is ± 0.15 mm unless specified.
3. This drawing is seen from the upper side of the printer.
4. The flatness of printer mounting plate shall be within 0.1mm.
5. * \varnothing dimension is the center of paper entrance for MCL304. The shape of entrance is reference dimension, which dose not touch to paper.
6. \odot shows an installation standard line of this printer.
7. Use 3-M3 when you install the printer from upper side.
8. Use this hole and oval hole when you install the printer from bottom side. (Printer mechanism has 2-M3 burring.) Also fix the front of platen side by a hook on the mounting plate.

Figure 3 FTP-642MCL301/302 mounting dimensions

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7. Connector Specifications

7.1 Thermal Head

(1) Connectors used

Mechanical unit side : B16B-PH-K-S-2.2 (made by J.S.T) or equivalent

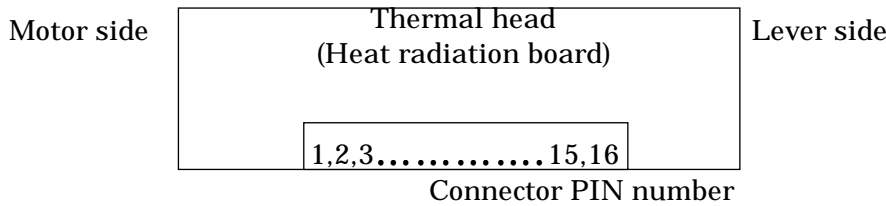
Remote (housing) side : PHR-16 (made by J.S.T) or equivalent

(2) Pin assignment on the mechanical unit side

Connector A:

Number	Symbol	Signal name
1	VH	Head drive power
2	VH	Head drive power
3	GND	Ground
4	GND	Ground
5	*STB 1	Strobe 1
6	*STB 2	Strobe 2
7	*STB 3	Strobe 3
8	TH*1	Thermistor
9	*STB 4	Strobe 4
10	*LAT	Data latch
11	*STB 5	Strobe 5
12	VDD	Logic power
13	CLK	Clock
14	DIN	Data in
15	GND	Ground
16	VH	Head drive power

*1) One end of the thermistor is connected to the ground.



(3) Notes

- 1) Pull up the five strobe signals with about 22kΩ.
- 2) Pull down the latch, data input, and clock signals with 22kΩ.
- 3) Don't connect or disconnect a connector with the power turned on.
- 4) Don't connect or disconnect a connector 11 or more times.
- 5) Don't strain connector.

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7.2 Paper Feed Motor

(1) Connectors used

Motor side(housing) : PHR-4 (made by J.S.T) or equivalent

Remote side: B4B-PH-PH-K-S (made by J.S.T) or equivalent

(2) Pin assignment on the motor side

Number	Symbol	Signal name
1	*B	Excitation signal *B
2	B	Excitation signal B
3	*A	Excitation signal *A
4	A	Excitation signal A

7.3 Sensor Connector

(1) Connectors used

Sensor side(housing) : PHR-5 (made by J.S.T) or equivalent

Remote side: B5B-PH-K-S (made by J.S.T) or equivalent

(2) Pin assignment on the sensor side

Number	Symbol	Signal name
1	VSEN	Power for the paper sensor
2	PHE	Photointerrupter emitter
3	PHK	Photointerrupter cathode
4	SW1	Head up detection switch 1
5	SW2	Head up detection switch 2

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8. Thermal Head Specifications

(1) General Characteristics

- | | |
|-------------------------|---|
| 1. Method | : Thermal line dot method |
| 2. Total number of dots | : 832 dots/line |
| 3. Dot pitch | : 0.125 mm (Vertical) x 0.125 mm (Horizontal) |
| 4. Dot dimensions | : 0.110 x 0.132 mm |
| 5. Average resistance | : 1500 Ω±15 % |

(2) Maximum rating

- | | |
|--|---|
| 1. Maximum voltage applied | : 27V |
| 2. Maximum energy applied | : 0.352 mJ/dot
(Vset=24.0 V, Ton=0.95 ms, Tcy=2.5ms) |
| 3. Maximum board temperature | : 70°C (thermistor temperature) |
| 4. Maximum number of concurrently energized dots | : 384 dots |

(3) Electrical characteristics

- | | |
|-------------------------------|--------------------------------|
| 1. Circuit block diagram | : Figure 4 |
| 2. Electrical characteristics | : Table 1 |
| 3. Timing chart | : Figure 5 |
| 4. Equivalent circuit | : Figure 6 |
| 5. Driver formation | : 64 bits x 13 drivers |
| 6. data transfer method | : Single-input serial transfer |
| 7. Data input frequency | : 5.0 MHz or lower |
| 8. Power supply for driver | : 5 V ± 5% at 0.2 A |
| 9. Printing method | : Independent 5-enable method |

(4) Electrical operating conditions (nominal ratings)

- | | |
|--|--|
| 1. Power applied (Po) | : 0.370 W/dot |
| 2. Width of pulse applied (Ton) | : 0.73 msec |
| 3. Energy applied (Eo) | : 0.27 mJ / dot (25°C) |
| 4. Printing cycle period | : 2.5 msec (at 25°C, 2-part divided drive) |
| 5. This can be shortened by using self-hysteresis method | |
| Voltage applied (VH) | : 24.0V |
| 6. Current consumption | : 5.9 A (peak value at 24.0 V) |

Notes :

Energy calculation formula

Head average Resistance value (Rav)	Power applied (P)	Power loss (PL)	Voltage drop (VL)
1500±15%	0.370 W / dot	0.013 W / dot	0.85 V

$$P = \frac{(VH - VL)^2}{Rav} + PL$$

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(5) Thermistor characteristics

- 1) Thermistor constant (B) : 3950 k ± 2%
- 2) Resistance value R25 : 30 kΩ ± 5%
- 3) Operating temperature range : -20 to 80°C
- 4) Heat time constant : within 30 seconds (in air)
- 5) Temperature characteristics : $R_X = R_{25} \times \text{EXP}\{ B \times (1/T_X - 1/T_{25}) \}$
(T = Absolute temperature)

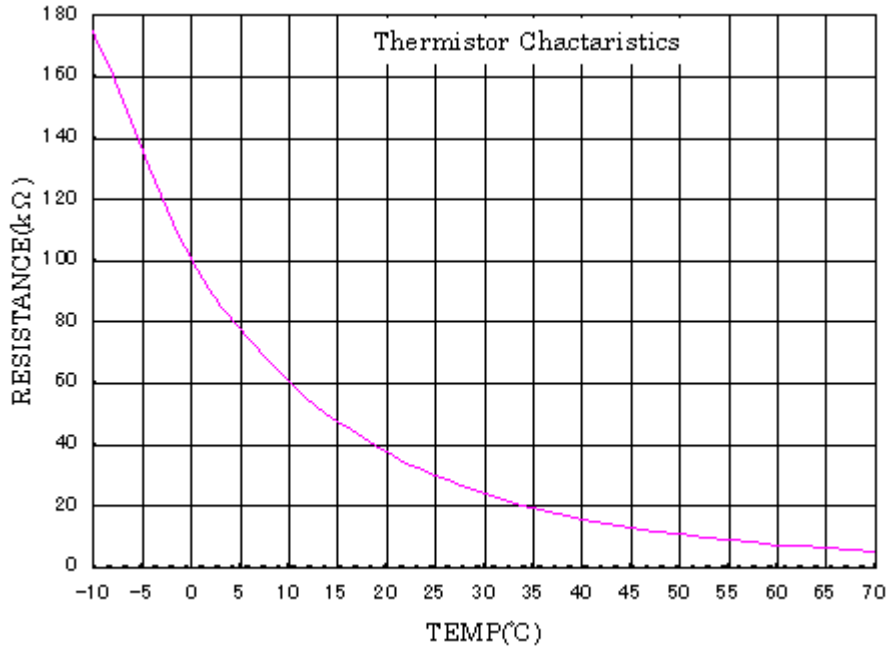


Figure 3 Temperature characteristics of thermistor

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(6) Notes on use

- 1) Control the head board (thermistor) temperature within the specified temperature if printing characters at a high printing rate.
- 2) It is recommended to turn VH off if the printer is in standby mode so that ions and noise does not damage the thermal head.
- 3) Control surge noise between VH and GND so that it does not exceed 32V.
- 4) Control the printer so that the thermal head does not overheat if a line to the thermistor is cut.
- 5) Do not apply pulse noise that is 2 V or greater and/or 20 ns or more to the signal pins.
- 6) It is recommended to route the lines from VH to the thermal head and GND to the thermal head using wires 300mm or less and 15mΩ or less that are separated from the other signal lines.
- 7) Control the CLK, LAT, DIN, and STB signals using the C-MOS (74HC240 or similar).
- 8) Install an aluminum electrolytic capacitor with approximately 15 V withstand voltage and 33 μF between VDD and GND to prevent noise.
- 9) Turn on the VDD first, then the VH. Turn off the VH first, then the VDD.

A

B

C

D

E

A

B

C

D

E

F

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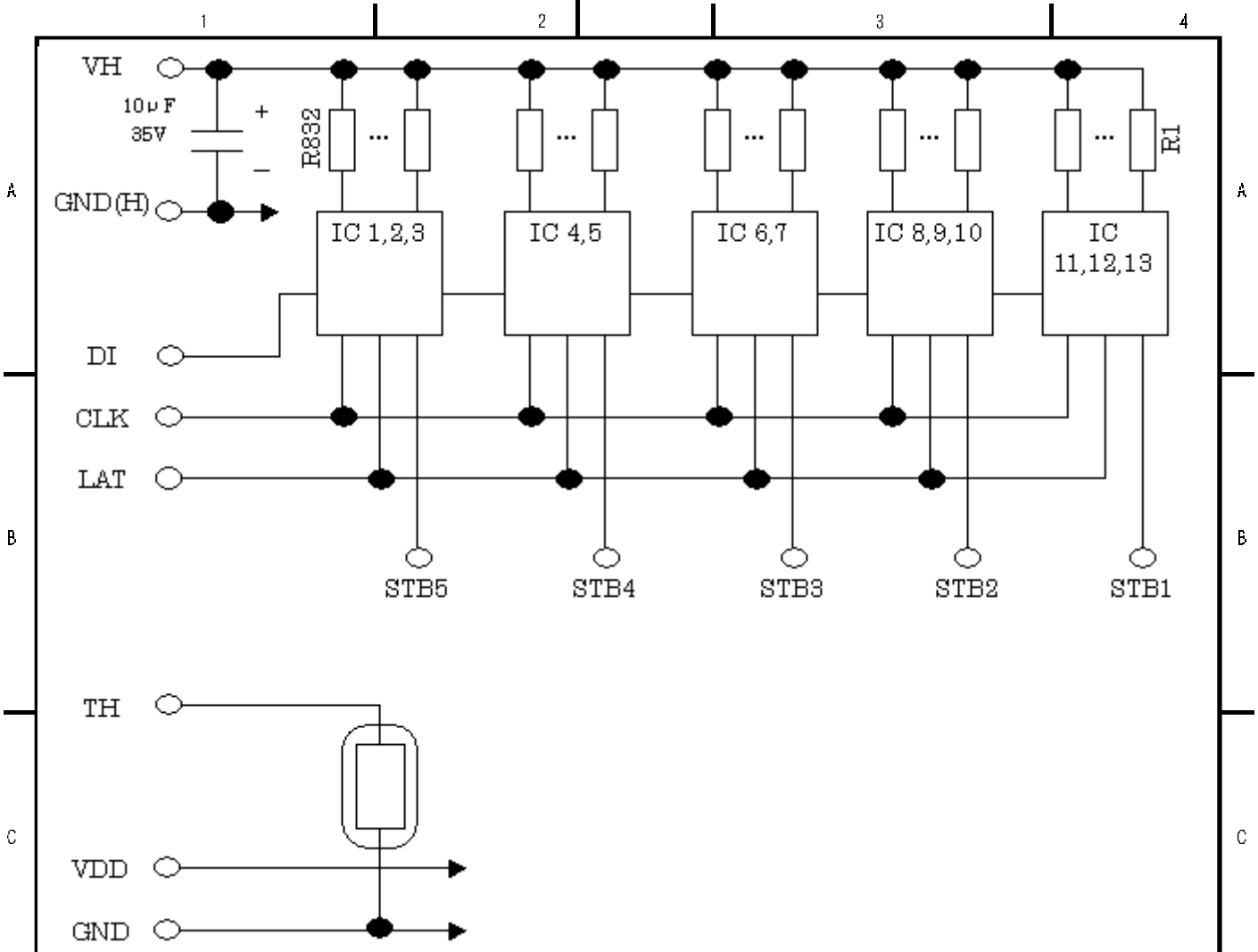


Figure 4 Circuit block diagram

Notes:

1. VH is the power for the head.
2. VDD is the power for the logic.
3. GND is the power ground.
4. R1 to R832 are heating resistance elements.

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Table 1 Electrical characteristics

Item	Symbol	Minimum	Typical	Maximum	Unit	Conditions
Average resistance Value	Rave	1275	1500	1725	Ω	
Output supply Voltage	Vset	-	24.0	27.0	V	Standard printing conditions The maximum rating is 27.0 V.
Supply voltage	VDD	4.5	5.00	5.5	V	
High input voltage	Vih	0.8xVDD	-	VDD	V	ENB, DI, LAT, CLK
Low input voltage	Vil	0.0	-	0.2xVDD	V	Same as above
High input current	Iih	-	-	1.0	μA	DI
		-	-	13.0	μA	CLK, LAT
		-	-	52.0	μA	ENB
Low input current	Iil	-	-	-1.0	μA	DI
		-	-	-13.0	μA	CLK, LAT
		-	-	-949.0	μA	ENB
Driver leakage current	IL	-	-	10.0	μA /dot	VDD=5.0V, VH=27V
Driver saturation voltage	Voon	-	-	2.0	V	VDD=5.0V, VIo=45mA
Maximum transfer Frequency	fd	-	-	5.0	MHz	
Data setup time	T1	70.0	-	-	ns	See Figure 4, "Timing chart."
Data holding time	T2	30.0	-	-	ns	Same as above
Latch setup time	T3	300.0	-	-	ns	Same as above
Latch pulse width	T4	200.0	-	-	ns	Same as above
Strobe setup time	T5	1.5	-	-	μs	Same as above
Propagation delay Time	T6	-	-	3.0	μs	Same as above
Propagation delay Time	T7	-	-	3.0	μs	Same as above

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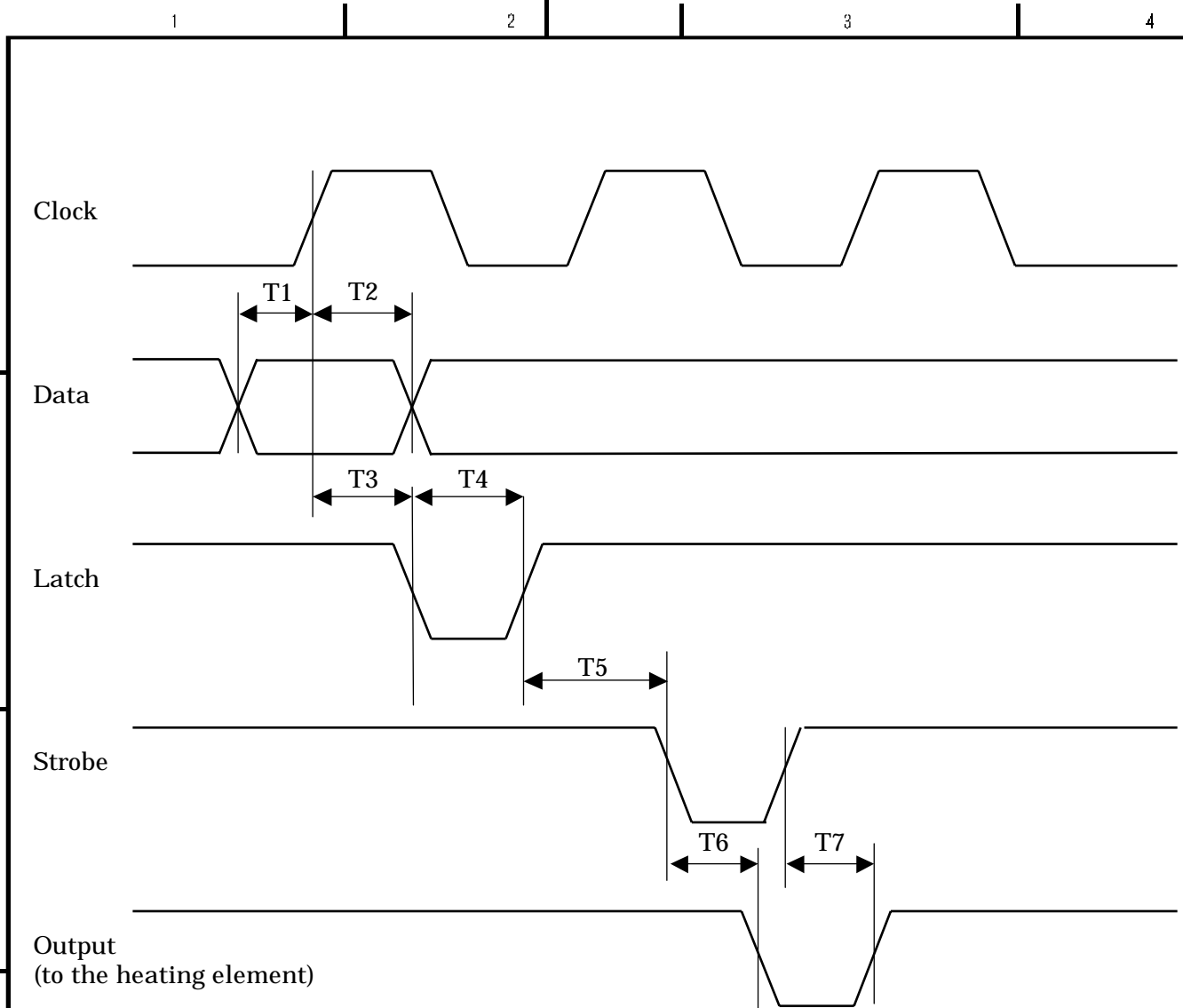
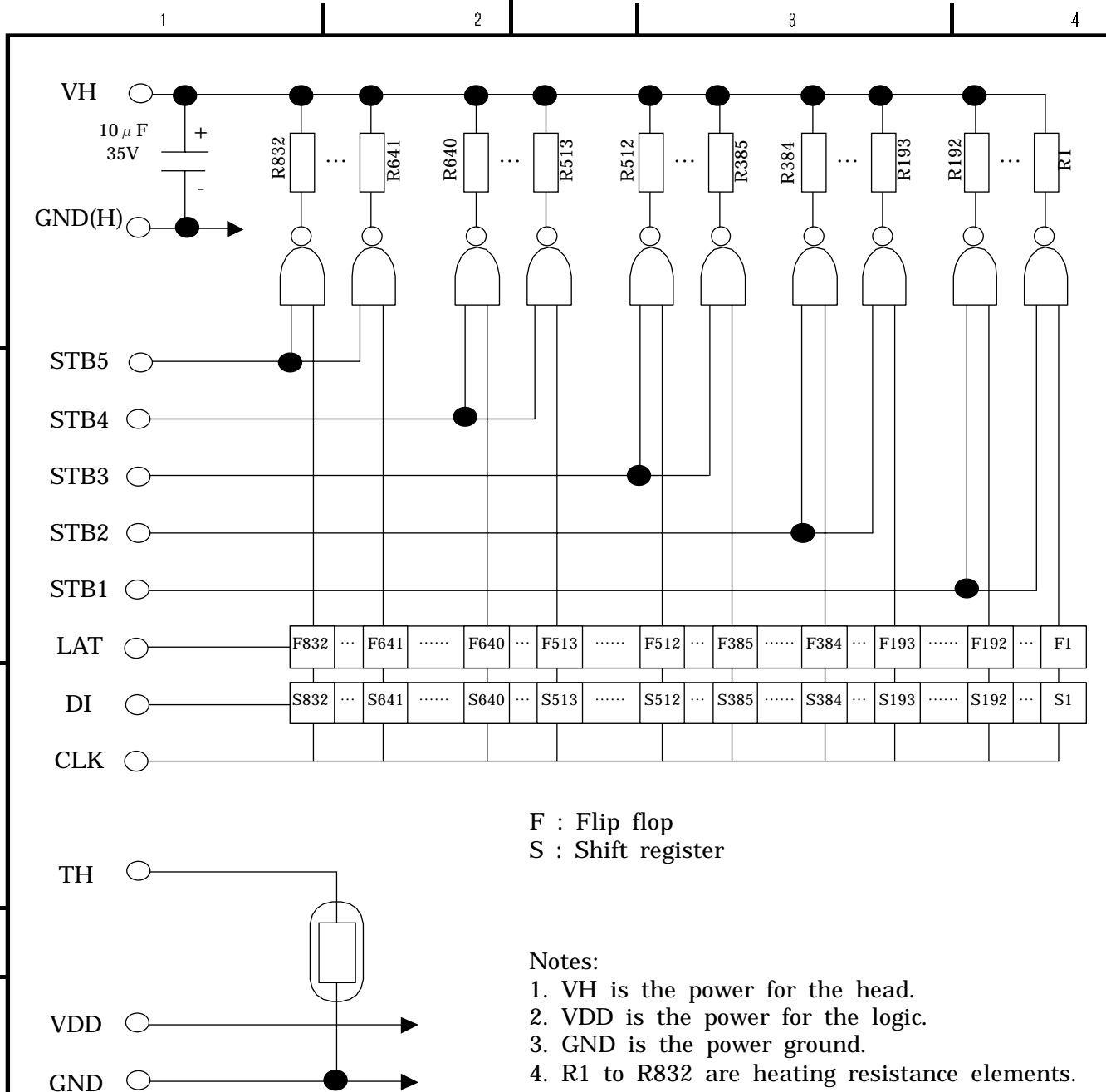


Figure 5 Timing chart

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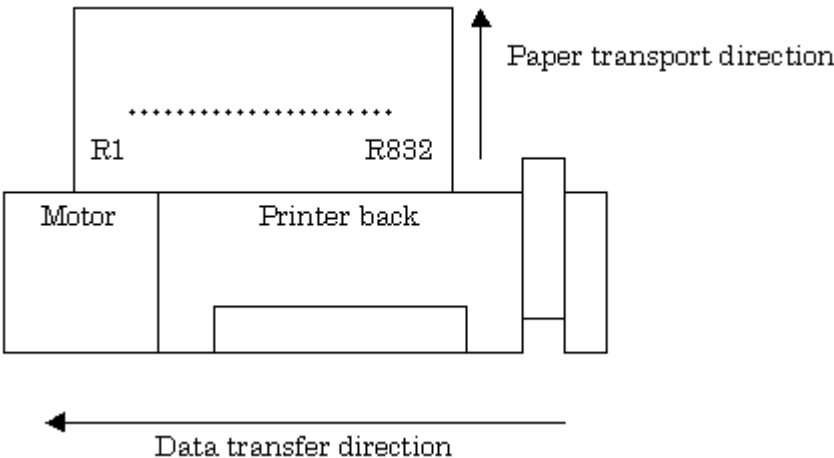
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F : Flip flop
 S : Shift register

- Notes:
 1. VH is the power for the head.
 2. VDD is the power for the logic.
 3. GND is the power ground.
 4. R1 to R832 are heating resistance elements.

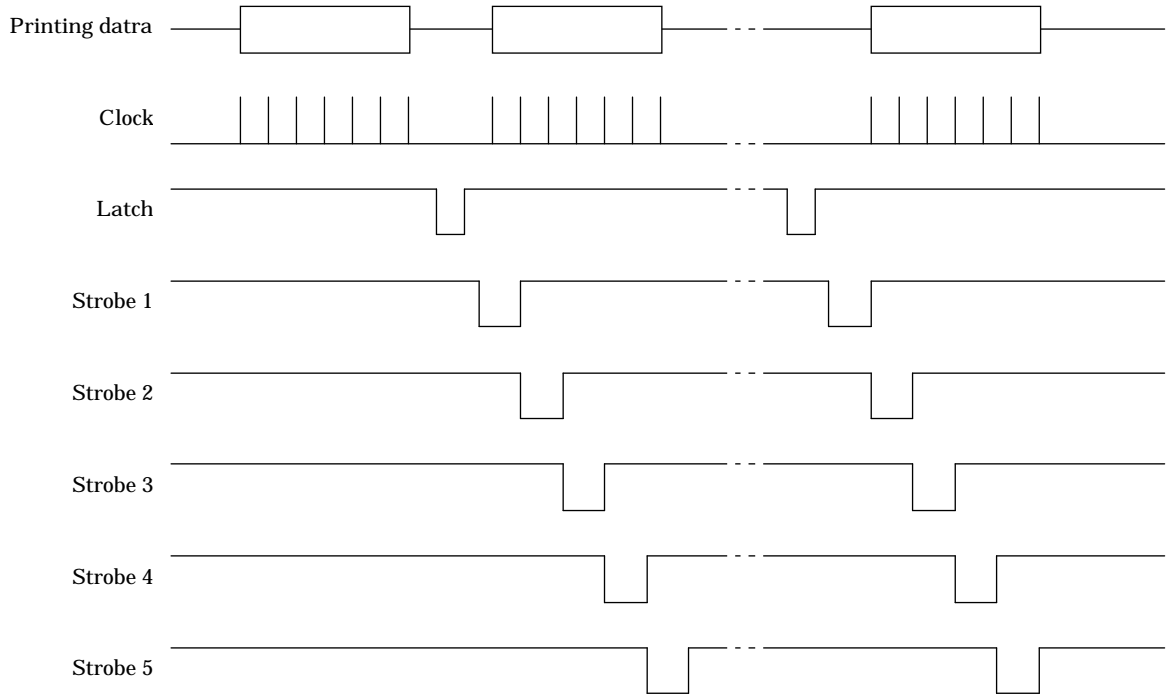
Figure 6 Electric circuit block diagram



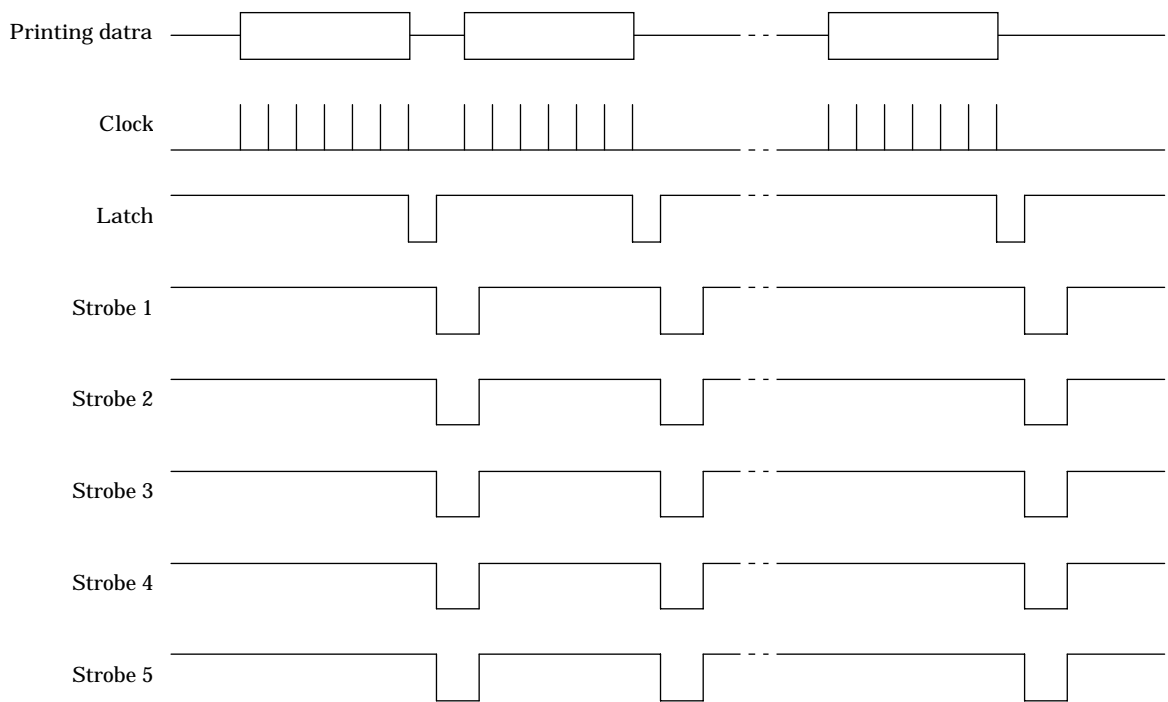
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a. At standard drive



b. At high-speed drive



Note:
The head current consumption increases at high-speed drive.

Figure 7 Control timing

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Temperature characteristics of FTP-6x2MCL series thermistor and application width

Temperature	Thermistor resistance value (kΩ)	Printing speed 80 mm/sec		Printing speed 50 mm/sec		Printing speed 30 mm/sec	
		Application width (ms)	Energy (mj)	Application width (ms)	Energy (mj)	Application width (ms)	Energy (mj)
0	100.99	0.867	0.310	1.009	0.360	1.245	0.445
5	77.85	0.822	0.294	0.956	0.342	1.180	0.422
10	60.57	0.777	0.278	0.904	0.323	1.116	0.399
15	47.53	0.732	0.262	0.852	0.304	1.052	0.376
20	37.61	0.682	0.244	0.794	0.284	0.980	0.350
25	30.00	0.638	0.228	0.742	0.265	0.916	0.327
30	24.11	0.598	0.214	0.696	0.249	0.859	0.307
35	19.51	0.563	0.201	0.655	0.234	0.808	0.289
40	15.89	0.538	0.192	0.626	0.224	0.773	0.276
45	13.03	0.513	0.183	0.597	0.213	0.737	0.263
50	10.75	0.493	0.176	0.574	0.205	0.708	0.253
55	8.92	0.478	0.171	0.556	0.199	0.687	0.245
60	7.45	0.463	0.165	0.539	0.193	0.665	0.238
65	6.25	0.453	0.162	0.527	0.188	0.651	0.233
70	5.27	0.438	0.156	0.510	0.182	0.630	0.225
75	4.47	0.433	0.155	0.504	0.180	0.622	0.222
80	3.80	0.423	0.151	0.493	0.176	0.608	0.217

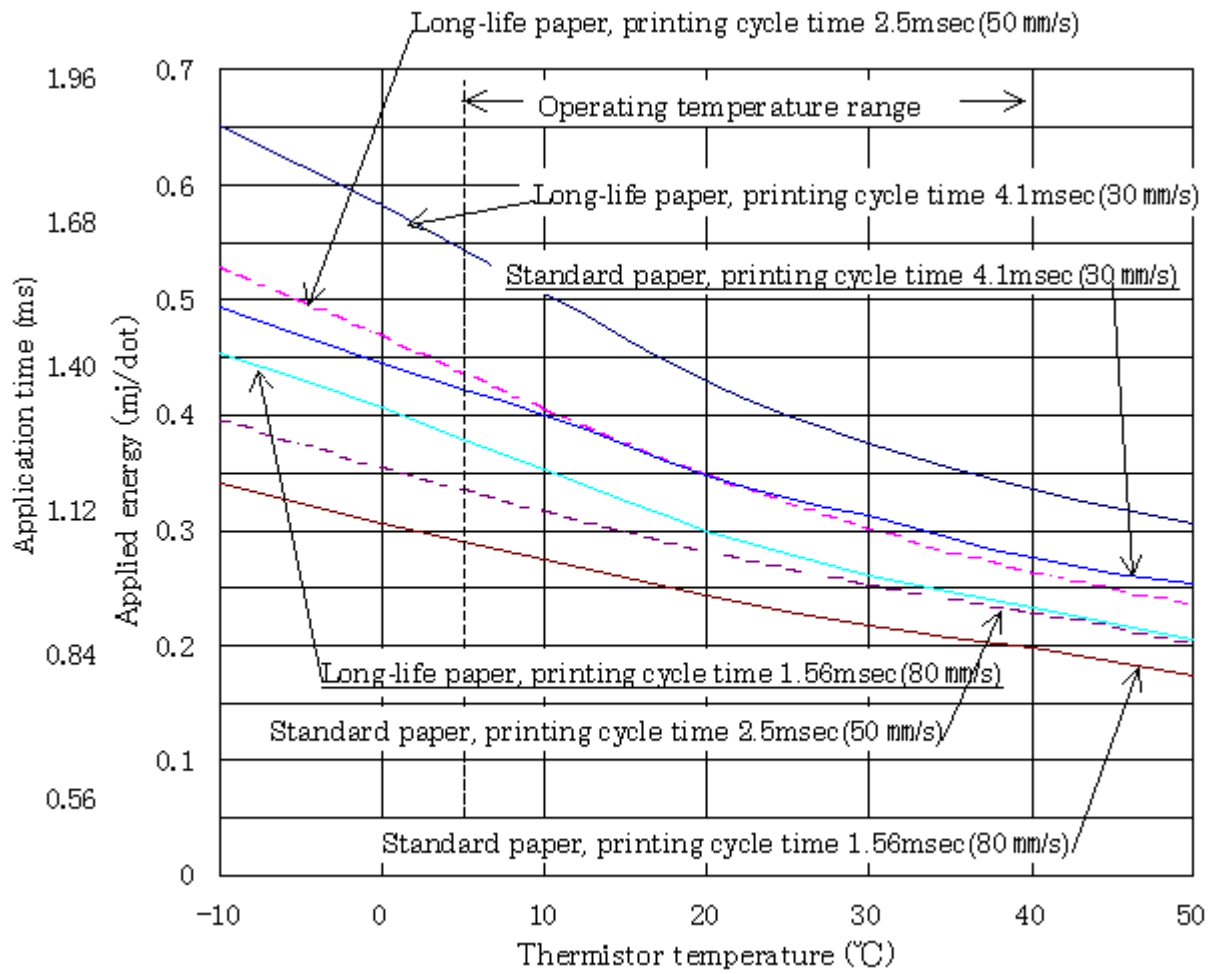
“Condition”

Supply voltage : 24 V
 Paper : Standard paper (PD150R)
 Average resistance value : 1500 Ω

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Temperature-applied energy characteristics of FTP-6x2MCL series

Condition

Head supply voltage : 24V

Standard paper : PD150R

Long-life paper : AFP-235

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9. Stepping Motor Specifications

(1) General specifications (motor as a single unit)

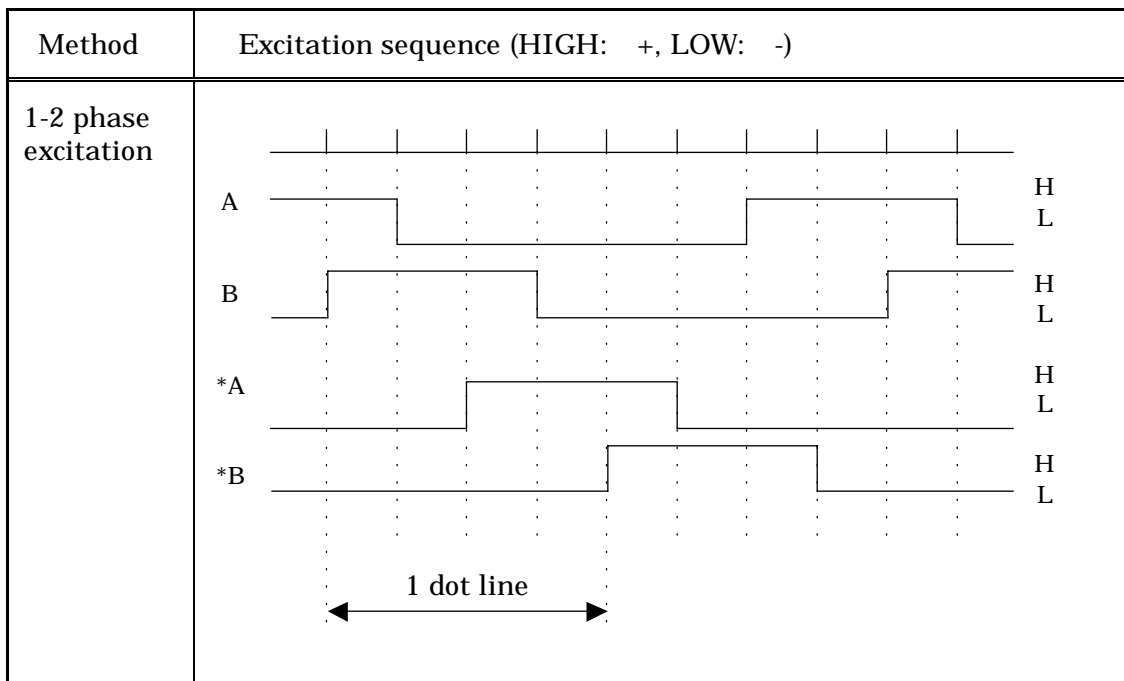
Item	Specification
Type	Permanent magnetic type
Number of phases	2 phases (bipolar specification)
Step angle	9 ° at 1-2 phase excitation
Coil resistance/phase	6.0Ω±10%
Rated voltage	DC24 V
Maximum input	1.5 W

(2) Stepping motor drive method

- 1) Drive the stepping motor by bipolar 1-2 phase excitation.
- 2) Number of steps per dot line printed

Excitation method	Number of steps	Rotation angle
1-2 phase excitation	4	9 degrees/step

3) The excitation method for reference is shown below.



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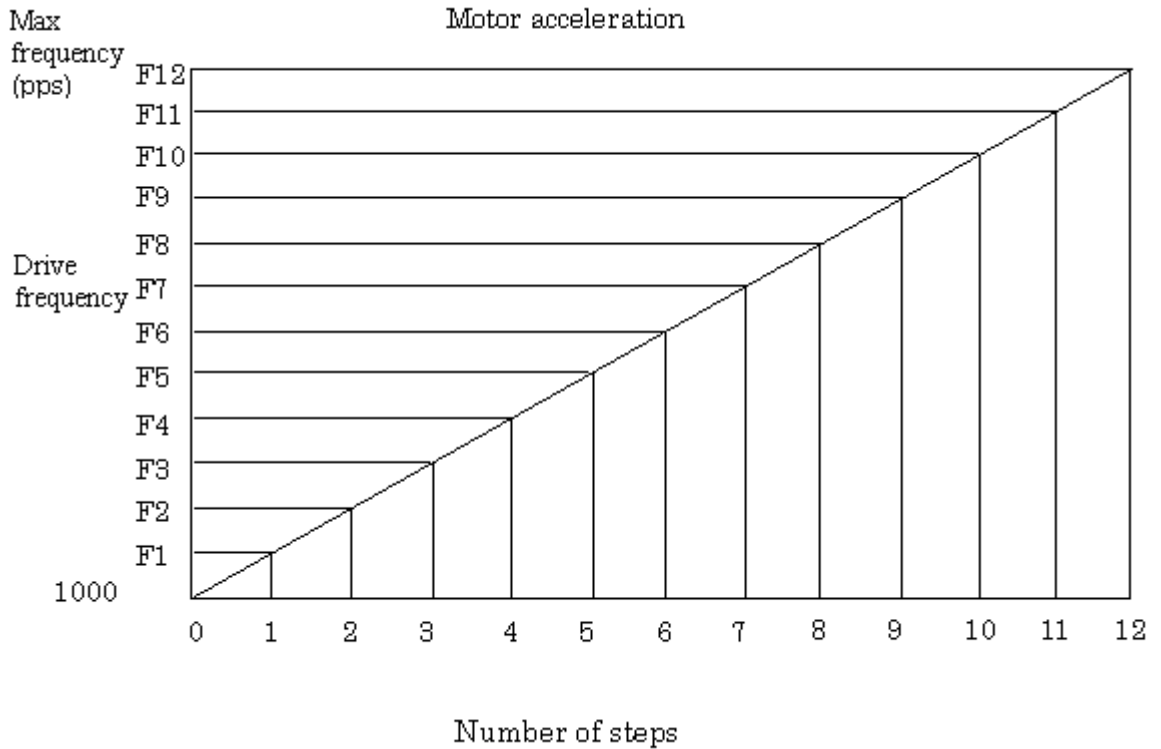
(3) Motor control of FTP-6x2MCL series

1) Motor drive conditions

ITEM	CONTENTION
Drive method	Bipolar 1-2 phase drive
Drive current	480 mA
Drive voltage	24 V

2) Acceleration control method

(a) Control motor acceleration and deceleration as follows.



- (b) If motor excitation is off when acceleration is started, feed current though the motor for about eight ms beforehand.
- (c) After printing, wait in the 1-phase excitation state for about 10 seconds and hold the paper position until the start of the next printing.
- (d) After 10 or more seconds have passed from a printing end, turn off motor excitation to suppress heating.
- (e) If a trouble occurs, turn off the motor current.

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(4) Motor drive condition

1) In this motor, coil resistance is suppressed low to prevent the current rise waveform from being dulled by the L component of the motor coil at high-speed drive. Drive this motor by a constant-current circuit (up to 500 mA) according to the drive circuit example to obtain stable torque over resistance value variation, voltage, etc.

Excessive current generates abnormal heat and excessive torque to damage the mechanical unit. Don't allow current that exceeds the required to flow.

2) Check the effect of temperature, humidity, paper type, etc. on load variation before determining the motor drive conditions. Motor drive with excessive torque may damage the gear at paper lock or other.

3) At low-speed drive (low drive frequency), abnormal noise or torque drop may occur because of motor resonance. Perform full evaluation and check to use a 500 pps or lower drive frequency.

4) Control acceleration and deceleration when rapidly changing the motor drive speed at

5) printing start and when starting printing after motor excitation is turned off.

6) Perform dummy feed of several dot lines to match the motor excitation phase and remove the effect of the drive transmission system when starting printing after motor excitation is turned off.

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(5) Notes

- 1) If the motor is stopped and motor excitation is discontinued during printing, the print may be separated because of the elasticity of the rubber roller when the motor is restarted. Print crush or white line insertion may occur. When print continuity is required, print all data at one time instead of stopping printing halfway. The above rubber roller deformation and other effect can also be reduced by feeding minute current in the standby state. In this case, the current as a guide is 150 mA
- 2) Turn off excitation to leave the printer unused for long time. The motor, drive element, or other may be heated.
- 3) Hold the motor side wall temperature 90°C or lower in use. Excess of 90°C may damage the coil in the motor.
- 4) When an abnormal condition occurs, stop printer drive as early as possible.
- 5) This printer feeds one dot line by four steps. Therefore, in motor drive by 1-2 phase excitation, control the motor so that stop occur in the 1-phase excitation state and start occurs in the 2-phase excitation state to save power and stabilize operation.
- 6) Printing operation with no paper and the head down may wear the rubber roller or damage the head. Don't perform printing in this condition.

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(6) Example of stepping motor drive circuit

Figure 10 shows an example of the bipolar constant-current drive circuit.

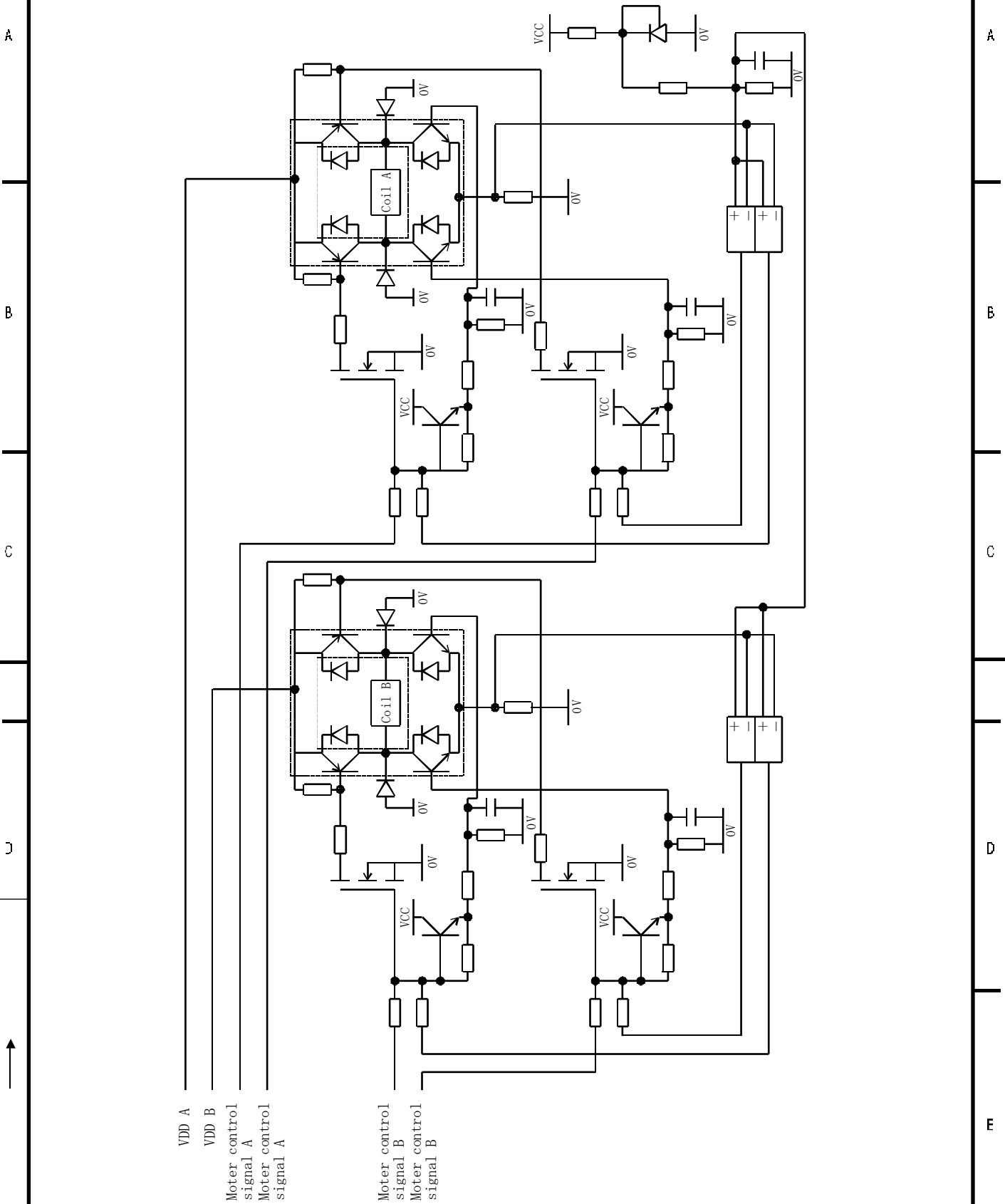


Figure 10 Motor drive circuit

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10. Photointerrupter Specifications

The main purpose of this photointerrupter is to position the paper by mark detection. This photointerrupter can also be used to detect no paper condition.

(1) Absolute maximum ratings

Item		Symbol	Rated value	Unit
Input	Forward current	I_F	50	mA
	Reverse voltage	V_R	5	V
	Allowable loss	P	70	mW
Output	Voltage between collector and emitter	V_{CEO}	20	V
	Voltage between emitter and collector	V_{ECO}	5	V
	Collector current	I_C	20	mA
	Collector loss	P_C	70	mW

(2) Electrooptical characteristics

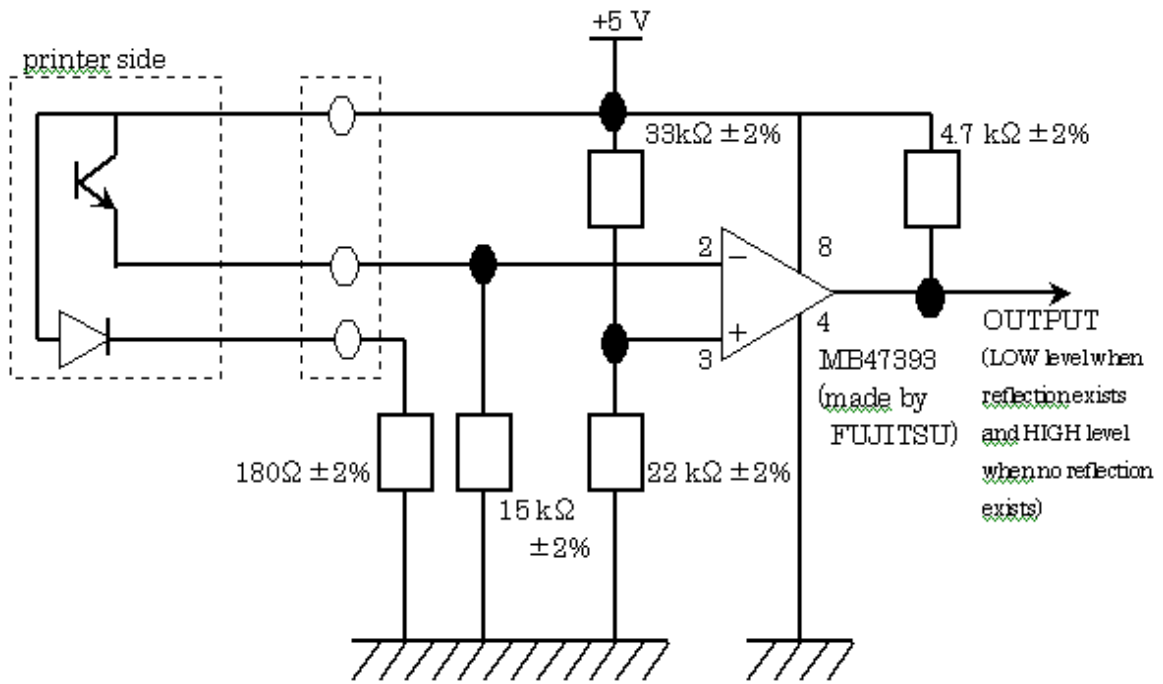
(25°C)

Item	Symbol	Minimum value	Typical value	Maximum value	Unit	Conditions
Input	Forward voltage	V_F	1.0	1.2	1.4	V $I_F=20\text{ mA}$
	Reverse current	I_R	-	-	10	μA $V_R=3\text{ V}$
Output	Dark current	I_{CEO}	-	-	200	nA $V_{CE}=10\text{ V}$
Transmission Characteristics	Photoelectric current	I_C	260	-	1100	μA $V_{CE}=5\text{ V}, I_F=10\text{ mA}$
	Leakage current	I_{LEAK}	-	-	1	μA $V_{CE}=5\text{ V}, I_F=20\text{ mA}$
	Response time (rise)	t_r	-	5	-	μs $V_{CE}=5\text{ V}, I_C=1\text{ mA}$
	Response time (fall)	t_f	-	5	-	μs $R_L=100\Omega$

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(3) Example of external connection circuit



11. Microswitch Specifications

Microswitches are built in to detect head up.

Item	Specification
Rated voltage	DC 30V
Rated current	0.1 A
Minute load capacity	DC5 V, 1 mA
Contact resistance	200 mΩ or less
Contact material	Gold

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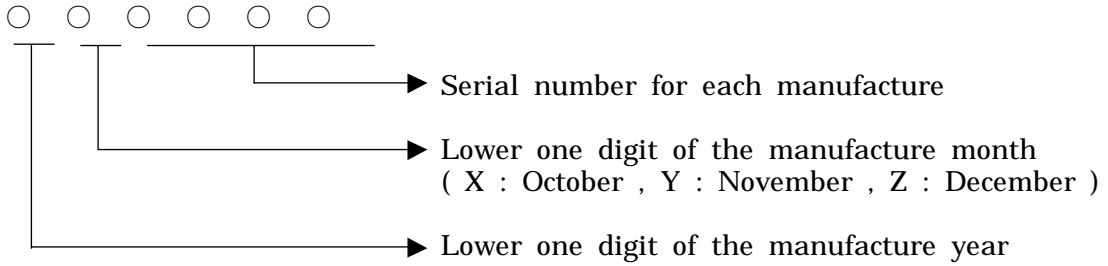


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12. Marking

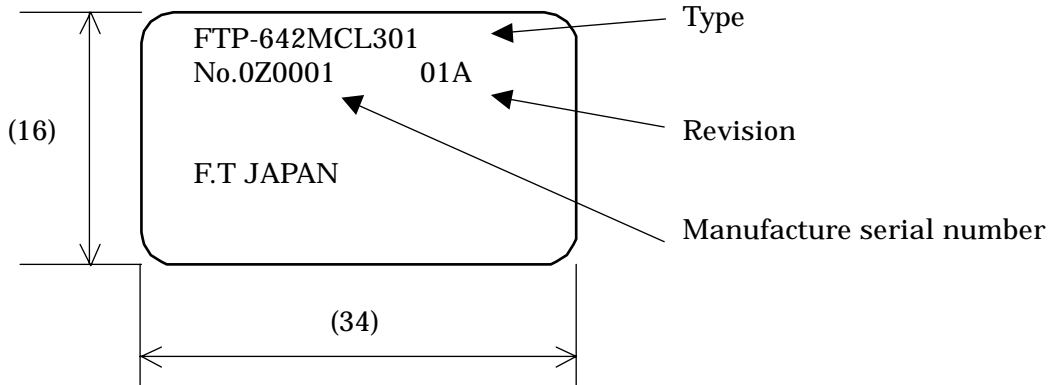
11.1 Type and Serial Number Marking label

- (1) Contents: The type, manufacture serial number, and revision number are marked.
- (2) Application place: This label shall be applied on the side of the main body of the mechanical unit.
- (3) Marking method: The type number, serial number, and revision number shall be marked by stamping.
- (4) Serial number marking: 6-digits serial number shall be marked in the following format:



- (5) Revision number marking: Mark the revision of the printer.

- (6) Marking example: A marking example is shown below.



13. Packing

- (1) Packing form: Put each unit in an antistatic bag and pack it in the dedicated packing box.
- (2) Dimensions: Conform to the F&T standard.
- (3) Number of units piled: Up to three units can be piled up in horizontal position.
- (4) Marking: Mark the type and quantity on the surface of the packing box.

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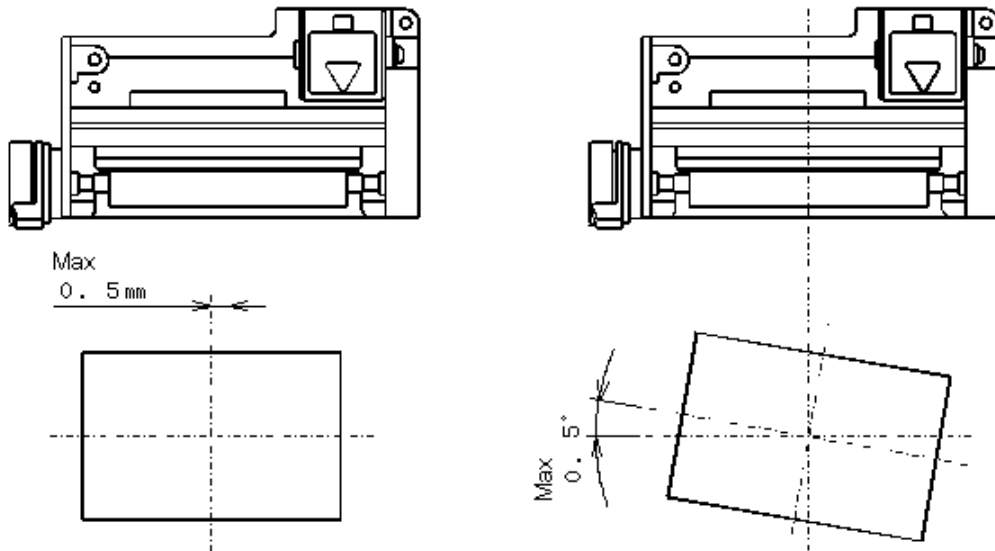
14. Notes for Handling

(1) Notes for paper loading and unloading

Load the paper so that its shaft is as parallel with the printer as possible.
(See the figure below)

Adjust paper ejection so that it is ejected smoothly without hitting the cover or other.

Without these treatments, trouble such as paper snaking, printing position misalignment, and paper jam may occur in printing.



(2) Notes for storage

For long-time storage (half year or longer in room temperature), load paper and establish head up condition.

If the rubber roller remain in direct contact with the head and pinch roller for long time, the rubber roller may be partially deformed to cause uneven print darkness.

Do not place the printer in an environment in which condensation may occur with the power on for long time to prevent galvanic corrosion.

(3) Notes for mounting and setting

Secure the printer by 3 mounting holes using three M3.0 screws.
At this time, support the printer by the same plate (flatness : 0.1 or less).

Connect the mounting section on the motor side to the frame ground of the main body.

In securing, take care not to strain or deform the printer body.

A violation of these notes may cause trouble such as blurred printing, wavy paper, paper jam, and noise.

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(4) Back tension of recording paper

When using this printer with the F&T standard circuit, adjust the back tension of the paper at the printer paper entrance to approx.100g

Application of back tension that exceeds 100g may cause a paper jam or overload and damage the gear.

(5) Galvanic corrosion

If head voltage is applied with the paper wet, the head may be damaged because of galvanic corrosion. Do not place the printer in an environment in which condensation may occur with the power on for long time.

(6) Dust and drip

The structure of this printer is neither dust-proof nor drip-proof. Give a treatment against dust and drips to the mainframe side beforehand.

(7) Other

Lift the head up lever when paper is not loaded on the printer.

If the paper runs out during printing, stop printer operation to prevent printing with no paper. This causes printer failures.

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15. Other

- (1) Both sides shall consult to solve occurred problems based on this specification.
- (2) Both sides shall consult to make changes and additions incompatible with this specification.

In the range of compatibility, this printer may be changed without prior notice because this type is a standard type.

- (3) Preprinting

Consult on preprinting (printing on the paper) according to Appendix 1 beforehand.

The ink used, printing method, and drying method of preprinting may affect the print quality of the thermal printer largely.

- (4) Label feed

Do not feed labels backward by turning the knob in reverse direction or other because it may cause the label to adhere to the inside of printer.

- (5) Paper rolling direction

Roll the paper with the heat-sensitive side on the outside to make paper insertion easy and reduce the transport load at drive.

- (6) Paper perforation

Perforate paper from the heat-sensitive side to prevent printing failure or head life shortening because of a perforation burr or paper residues.

- (7) Head cleaning

Paper residues or foreign matter may shorten the life of the head or platen. Clean the printer periodically.

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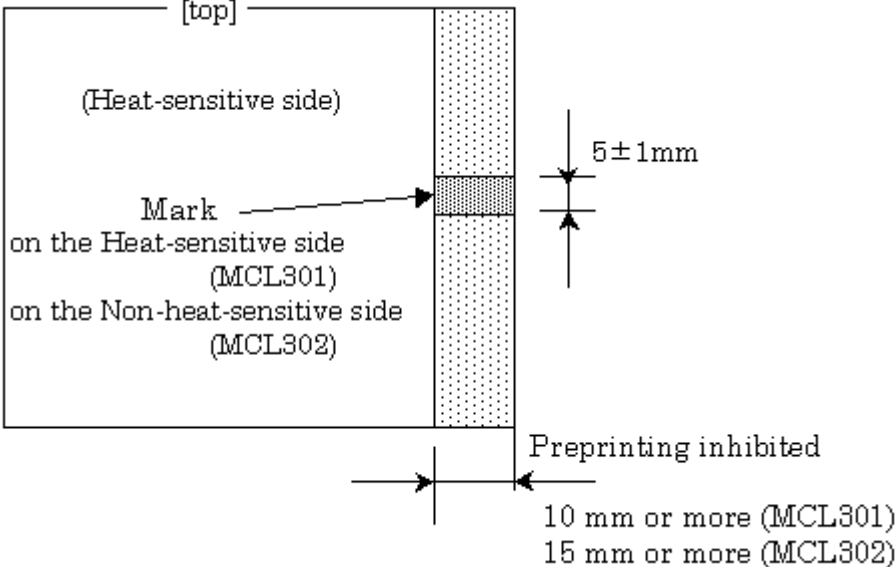
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Preprinting

1. Detecion mark position

Print the detection mark in a 5±1 mm x 10 mm (MCL301) and 15 mm (MCL302) or wider band as shown in the figure below.



2. Positioning mark preprinting

The mark color shall be black and the density shall be 7% or lower reflection factor and PCS0.9 or higher. Use oil ink and remove unevenness. Multiple coating is recommended to raise the PCS value.

The density measuring instrument and value are as follows:

PCS measuring instrument : Macbeth reflection-type densitometer PCM-II
(used filter : D range 900 nm)

3. Preprinting inhibition

Preprinting on the mark detection area (10 mm from the right edge) is inhibited. If this preprinting is required, select ink in the range of the wavelength (700 to 1000 nm) used by the photointerrupter and so that the reflection factor is 80% or higher.

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4. Notes for preprinting

The characteristics of heat-sensitive paper differ those of general printing paper and no-carbon paper. Note the following in print processing :

A. Printing method

Use the UV printing method because heat-sensitive paper has poor ink dryability.

B. Ink

(1) Use ink that doesn't have bad effect such as residue adhesion, head wearing, and sticking on the thermal printer.

(2) Use ink that contains 100 ppm or less of CI ions.

Recommended ink : RNC type by F&K TOKA

(3) Take care of the ink tack because the surface strength of the heat-sensitive layer is lower than general printing paper. Use 6.0 as the ink tack for general heat-sensitive paper or the same level as no-carbon paper for high-storage heat-sensitive paper.

(4) Don't apply an excessive amount of ink. An excessive amount of ink causes printing or coloring failure or sticking.

(5) Use heat-resistant ink material that doesn't perform cooling. Also use such ink for the non-heat-sensitive side.

(6) After printing, check that the ink adheres to the paper. Manage wetting water carefully because in general, UV ink tends to yield to water.

(7) Avoid ink transfer and blocking.

(8) Ensure that the preprint isn't peeled by water or alcohol.

C. Wetting water

(1) Manage wetting water carefully because heat-sensitive paper tends to repel water.

(2) An excessive amount of IPA in the wetting water may cause color smudging to background. adjust the IPA amount to 5% or less for general heat-sensitive paper or 10% or less for high-strong heat-sensitive paper.

D. Other

(1) When using many UV lamps, take care of paper contraction (flow or width direction) or color smearing because of heat.

(2) Set the holding roller pressure of the drive roll high because the paper surface is slippery.

(3) Perform multiple printing to raise the PCS value of the positioning marker.

(4) Some preprinting causes sticking or the like. Be sure to perform evaluation and check on the actual machine.

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